Linear algebra: SVD Statistical Natural Language Processing 1

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Winter Semester 2025/2026

Quick recap

So far we reviewed:

- Vectors, matrices
- Operations on vectors and matrices: scalar multiplication, addition, dot product, matrix multiplication
- Matrices as operators (linear functions / transformations)
- Linearity and linear combinations
- Solving systems of linear equations, elimination
- Finding matrix inverse
- Linear regression
- Eigenvalues and eigenvectors

Today's plan

- Singular value decomposition
- Pseudo inverse

Orthogonal matrices

A short detour

- An orthogonal matrix is a square matrix whose columns (and rows) are othonormal (orthogonal unit) vectors
- Some interesting properties:
 - The product of two orthogonal matrices is another orthogonal matrix
 - Orthogonal matrices are invertible
 - Product of an orthogonal matrix with its transpose is the identity matrix

$$\mathbf{Q}^{\mathsf{T}}\mathbf{Q} = \mathbf{Q}\mathbf{Q}^{\mathsf{T}} = \mathbf{I}$$
$$\Rightarrow \mathbf{O}^{\mathsf{T}} = \mathbf{O}^{-1}$$

- Orthogonal matrices represent length-preserving transformations (rotations and reflections)
- Determinants of an orthogonal matrix is 1 or -1

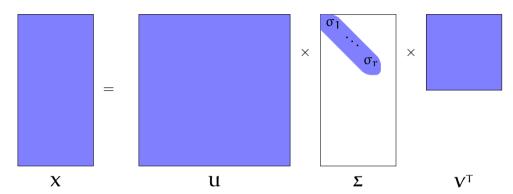
Singular Value Decomposition

• Singular value decomposition (SVD) of an $n \times m$ matrix X is

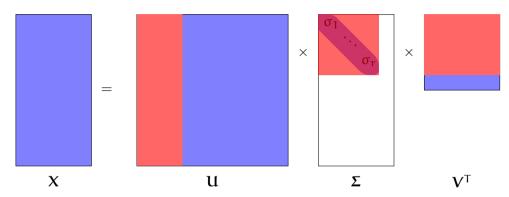
$$X = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^{\mathsf{T}}$$

- U is a $n \times n$ orthogonal matrix Σ is a $n \times m$ diagonal matrix of singular values V^T is a $m \times m$ orthogonal matrix.
- Singular vectors (columns) in \mathbf{U} are the eigenvectors of $\mathbf{X}\mathbf{X}^T$
- Singular vectors (rows) in V^T are the eigenvectors of X^TX

Singular Value Decomposition



Singular Value Decomposition



• Since n-r rows and m-r rows of Σ is 0, the decomposition does need the full matrices

Singular value decomposition and X^TX

• Assume $X = U\Sigma V^T$

$$\begin{split} \boldsymbol{X}^T \boldsymbol{X} &= (\boldsymbol{U} \boldsymbol{\Sigma} \boldsymbol{V}^T)^T \boldsymbol{U} \boldsymbol{\Sigma} \boldsymbol{V}^T \\ &= \boldsymbol{V} \boldsymbol{\Sigma}^T \boldsymbol{U}^T \boldsymbol{U} \boldsymbol{\Sigma} \boldsymbol{V}^T \\ &= \boldsymbol{V} \boldsymbol{\Sigma}^T \boldsymbol{\Sigma} \boldsymbol{V}^T \\ &= \boldsymbol{V} \boldsymbol{\Sigma}^2 \boldsymbol{V}^T \end{split}$$

Singular value decomposition and X^TX

• Assume $X = U\Sigma V^T$ $X^TX = (U\Sigma V^T)^TU\Sigma V^T$ $= V\Sigma^TU^TU\Sigma V^T$

$$= \boldsymbol{V}\boldsymbol{\Sigma}^2\boldsymbol{V}^T$$

 $= \mathbf{V} \mathbf{\Sigma}^{\mathsf{T}} \mathbf{\Sigma} \mathbf{V}^{\mathsf{T}}$

• Columns of V are eigenvectors of X^TX

Singular value decomposition and X^TX

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- Columns of V are eigenvectors of X^TX
- Values in the diagonal matrix Σ^2 are the eigenvalues of X^TX

 $= \mathbf{U} \mathbf{\Sigma}^2 \mathbf{U}^{\mathsf{T}}$

Singular value decomposition and XX^T

• Assume $X = U\Sigma V^T$ $XX^T = U\Sigma V^T (U\Sigma V^T)^T \\ = U\Sigma V^T V\Sigma^T U^T \\ = U\Sigma \Sigma^T U^T$

- Columns of U are eigenvectors of XX^T
- Values in the diagonal matrix Σ^2 are the eigenvalues of XX^T
- X^TX and XX^T share the eigenvalues

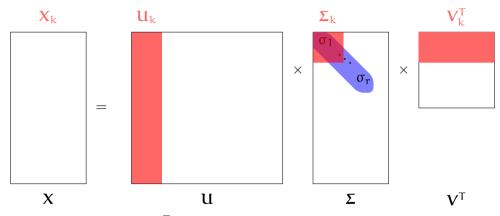
Computing SVD

- Find the eigenvalues and eigenvectors of X^TX
 - $-X^TX$ is symmetric (semi) definite, the eigenvectors can be chosen to be orthogonal unit vectors, the eigenvalues are positive
 - V is the collection of the eigenvectors (of $X^T \hat{X}$)
 - $\sigma_i = \sqrt{\lambda_i}$
- Knowing V and Σ ,

$$X = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^{\mathsf{T}}$$
$$X\mathbf{V} = \mathbf{U} \mathbf{\Sigma}$$
$$X\mathbf{V} \mathbf{\Sigma}^{-1} = \mathbf{U}$$

In practice there are more efficient ways to compute SVD

Low rank estimation of a matrix



 $X_k = U_k \Sigma_k V_k^\mathsf{T}$ is the best rank k estimation of matrix X

SVD: properties and applications

- Singular values are related to matrix norms
- SVD has a wide range of applications from image compression to document indexing to semantics of the words
- It is also a method for dimensionality reduction for visualizations
- A large number of statistical methods also rely on SVD (e.g., PCA, we will discuss later)
- The *condition number* of a matrix, an indication of numerical stability, depends on singular values
- SVD can be computed with good numerical accuracy, as a result it is also used for computing other quantities (e.g., matrix inverse)

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- A more general solution falls out of SVD

$$\times \begin{bmatrix} a & 0 & 0 & 0 \\ 0 & b & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} =$$

• We want matrix multiplication to get as close to I as possible. Consider the 3×4 diagonal matrix:

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- In general, if we use singular value decomposition $X^+ = V \Sigma^+ U^T$

Summary / next

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Next:

• A very short introduction to calculus

the SVD song

Further reading

Any of the linear algebra references provided earlier.